

Interpolation & Polynomial Approximation

Cubic Spline Interpolation III

Numerical Analysis (9th Edition)

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Beamer Presentation Slides

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Outline

1 Introduction to Clamped Splines

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- 1 Introduction to Clamped Splines
- 2 Existence of a Unique Clamped Spline Interpolant

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- 3 Clamped Cubic Spline Algorithm

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- 4 Clamped Cubic Spline approximating $f(x) = e^x$

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Introduction to Clamped Splines

Example: Clamped Cubic Spline

- In an earlier [▶ Example](#) we found a natural spline S that passes through the points $(1, 2)$, $(2, 3)$, and $(3, 5)$.
- Construct a clamped spline s through these points that has $s'(1) = 2$ and $s'(3) = 1$.

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Starting Point

Let

$$s_0(x) = a_0 + b_0(x - 1) + c_0(x - 1)^2 + d_0(x - 1)^3$$

be the cubic on $[1, 2]$ and the cubic on $[2, 3]$ be

$$s_1(x) = a_1 + b_1(x - 2) + c_1(x - 2)^2 + d_1(x - 2)^3$$

and then use the various conditions to determine the 8 constants.

Introduction to Clamped Splines

$$s_0(x) = a_0 + b_0(x - 1) + c_0(x - 1)^2 + d_0(x - 1)^3$$

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Solution (1/2)

Assemble the various conditions:

Introduction to Clamped Splines

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Assemble the various conditions:

$$2 = f(1) = a_0, \quad 3 = f(2) = a_0 + b_0 + c_0 + d_0$$

Introduction to Clamped Splines

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Solution (1/2)

Assemble the various conditions:

$$2 = f(1) = a_0, \quad 3 = f(2) = a_0 + b_0 + c_0 + d_0$$

$$3 = f(2) = a_1, \quad 5 = f(3) = a_1 + b_1 + c_1 + d_1$$

Introduction to Clamped Splines

$$\begin{aligned}s_0(x) &= a_0 + b_0(x-1) + c_0(x-1)^2 + d_0(x-1)^3 \\ s_1(x) &= a_1 + b_1(x-2) + c_1(x-2)^2 + d_1(x-2)^3\end{aligned}$$

Solution (1/2)

Assemble the various conditions:

$$\begin{aligned}2 = f(1) &= a_0, & 3 = f(2) &= a_0 + b_0 + c_0 + d_0 \\ 3 = f(2) &= a_1, & 5 = f(3) &= a_1 + b_1 + c_1 + d_1 \\ s'_0(2) &= s'_1(2) \Rightarrow b_0 + 2c_0 + 3d_0 = b_1\end{aligned}$$

Introduction to Clamped Splines

$$\begin{aligned}s_0(x) &= a_0 + b_0(x-1) + c_0(x-1)^2 + d_0(x-1)^3 \\ s_1(x) &= a_1 + b_1(x-2) + c_1(x-2)^2 + d_1(x-2)^3\end{aligned}$$

Solution (1/2)

Assemble the various conditions:

$$\begin{aligned}2 = f(1) &= a_0, & 3 = f(2) &= a_0 + b_0 + c_0 + d_0 \\ 3 = f(2) &= a_1, & 5 = f(3) &= a_1 + b_1 + c_1 + d_1 \\ s'_0(2) &= s'_1(2) & \Rightarrow & b_0 + 2c_0 + 3d_0 = b_1 \\ s''_0(2) &= s''_1(2) & \Rightarrow & 2c_0 + 6d_0 = 2c_1\end{aligned}$$

Introduction to Clamped Splines

Solution (2/2)

However, the boundary conditions are now

$$s'_0(1) = 2 \quad \Rightarrow \quad b_0 = 2 \quad \text{and} \quad s'_1(3) = 1 \quad \Rightarrow \quad b_1 + 2c_1 + 3d_1 = 1$$

Introduction to Clamped Splines

Solution (2/2)

However, the boundary conditions are now

$$s'_0(1) = 2 \Rightarrow b_0 = 2 \quad \text{and} \quad s'_1(3) = 1 \Rightarrow b_1 + 2c_1 + 3d_1 = 1$$

Solving this system of equations gives the spline as

$$s(x) = \begin{cases} 2 + 2(x-1) - \frac{5}{2}(x-1)^2 + \frac{3}{2}(x-1)^3, & \text{for } x \in [1, 2] \\ 3 + \frac{3}{2}(x-2) + 2(x-2)^2 - \frac{3}{2}(x-2)^3, & \text{for } x \in [2, 3] \end{cases}$$

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Unique Clamped Spline Interpolant

Theorem

If f is defined at $a = x_0 < x_1 < \cdots < x_n = b$ and differentiable at a and b , then f has a unique clamped spline interpolant S on the nodes $x_0, x_1, \dots, x_n$; that is, a spline interpolant that satisfies the clamped boundary conditions $S'(a) = f'(a)$ and $S'(b) = f'(b)$.

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Note: With $S_j(x) = a_j + b_j(x - x_j) + c_j(x - x_j)^2 + d_j(x - x_j)^3$, for each $j = 0, 1, \dots, n - 1$, the proof will rely on two equations established earlier, namely:

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$$b_j = \frac{1}{h_j}(a_{j+1} - a_j) - \frac{h_j}{3}(2c_j + c_{j+1})$$

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$$b_j = \frac{1}{h_j}(a_{j+1} - a_j) - \frac{h_j}{3}(2c_j + c_{j+1})$$

$$h_{j-1}c_{j-1} + 2(h_{j-1} + h_j)c_j + h_jc_{j+1} = \frac{3}{h_j}(a_{j+1} - a_j) - \frac{3}{h_{j-1}}(a_j - a_{j-1})$$

Unique Clamped Spline Interpolant

$$(A) \quad b_j = \frac{1}{h_j}(a_{j+1} - a_j) - \frac{h_j}{3}(2c_j + c_{j+1})$$

Proof (1/5)

Unique Clamped Spline Interpolant

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Proof (1/5)

Since $f'(a) = S'(a) = S'(x_0) = b_0$, Equation (A) with $j = 0$ implies

$$f'(a) = \frac{1}{h_0}(a_1 - a_0) - \frac{h_0}{3}(2c_0 + c_1)$$

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$$f'(a) = \frac{1}{h_0}(a_1 - a_0) - \frac{h_0}{3}(2c_0 + c_1)$$

Consequently,

$$2h_0c_0 + h_0c_1 = \frac{3}{h_0}(a_1 - a_0) - 3f'(a)$$

Unique Clamped Spline Interpolant

$$(A) \quad b_j = \frac{1}{h_j}(a_{j+1} - a_j) - \frac{h_j}{3}(2c_j + c_{j+1})$$

Proof (2/5)

Unique Clamped Spline Interpolant

$$(A) \quad b_j = \frac{1}{h_j}(a_{j+1} - a_j) - \frac{h_j}{3}(2c_j + c_{j+1})$$

Proof (2/5)

Similarly,

$$f'(b) = b_n = b_{n-1} + h_{n-1}(c_{n-1} + c_n)$$

Unique Clamped Spline Interpolant

$$(A) \quad b_j = \frac{1}{h_j}(a_{j+1} - a_j) - \frac{h_j}{3}(2c_j + c_{j+1})$$

Proof (2/5)

Similarly,

$$f'(b) = b_n = b_{n-1} + h_{n-1}(c_{n-1} + c_n)$$

so equation (A) with $j = n - 1$ implies that

$$\begin{aligned} f'(b) &= \frac{a_n - a_{n-1}}{h_{n-1}} - \frac{h_{n-1}}{3}(2c_{n-1} + c_n) + h_{n-1}(c_{n-1} + c_n) \\ &= \frac{a_n - a_{n-1}}{h_{n-1}} + \frac{h_{n-1}}{3}(c_{n-1} + 2c_n) \end{aligned}$$

Unique Clamped Spline Interpolant

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Similarly,

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so equation (A) with $j = n - 1$ implies that

$$\begin{aligned} f'(b) &= \frac{a_n - a_{n-1}}{h_{n-1}} - \frac{h_{n-1}}{3}(2c_{n-1} + c_n) + h_{n-1}(c_{n-1} + c_n) \\ &= \frac{a_n - a_{n-1}}{h_{n-1}} + \frac{h_{n-1}}{3}(c_{n-1} + 2c_n) \end{aligned}$$

$$\text{and} \quad h_{n-1}c_{n-1} + 2h_{n-1}c_n = 3f'(b) - \frac{3}{h_{n-1}}(a_n - a_{n-1})$$

Unique Clamped Spline Interpolant

Proof (3/5)

The equations

$$h_{j-1}c_{j-1} + 2(h_{j-1} + h_j)c_j + h_jc_{j+1} = \frac{3}{h_j}(a_{j+1} - a_j) - \frac{3}{h_{j-1}}(a_j - a_{j-1})$$

Unique Clamped Spline Interpolant

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The equations

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together with

$$2h_0c_0 + h_0c_1 = \frac{3}{h_0}(a_1 - a_0) - 3f'(a)$$

Unique Clamped Spline Interpolant

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The equations

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together with

$$2h_0c_0 + h_0c_1 = \frac{3}{h_0}(a_1 - a_0) - 3f'(a)$$

and

$$h_{n-1}c_{n-1} + 2h_{n-1}c_n = 3f'(b) - \frac{3}{h_{n-1}}(a_n - a_{n-1})$$

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$$2h_0c_0 + h_0c_1 = \frac{3}{h_0}(a_1 - a_0) - 3f'(a)$$

and

$$h_{n-1}c_{n-1} + 2h_{n-1}c_n = 3f'(b) - \frac{3}{h_{n-1}}(a_n - a_{n-1})$$

determine the linear system $\mathbf{Ax} = \mathbf{b}$:

Unique Clamped Spline Interpolant

Proof (4/5)

where

$$A = \begin{bmatrix} 2h_0 & h_0 & 0 & \cdots & \cdots & 0 \\ h_0 & 2(h_0 + h_1) & h_1 & \ddots & & \vdots \\ 0 & h_1 & 2(h_1 + h_2) & h_2 & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \ddots & 0 \\ \vdots & & \ddots & h_{n-2} & 2(h_{n-2} + h_{n-1}) & h_{n-1} \\ 0 & \cdots & \cdots & 0 & h_{n-1} & 2h_{n-1} \end{bmatrix}$$

Unique Clamped Spline Interpolant

Proof (5/5)

and

$$\mathbf{b} = \begin{bmatrix} \frac{3}{h_0}(a_1 - a_0) - 3f'(a) \\ \frac{3}{h_1}(a_2 - a_1) - \frac{3}{h_0}(a_1 - a_0) \\ \vdots \\ \frac{3}{h_{n-1}}(a_n - a_{n-1}) - \frac{3}{h_{n-2}}(a_{n-1} - a_{n-2}) \\ 3f'(b) - \frac{3}{h_{n-1}}(a_n - a_{n-1}) \end{bmatrix} \quad \text{with} \quad \mathbf{x} = \begin{bmatrix} c_0 \\ c_1 \\ \vdots \\ c_n \end{bmatrix}$$

Matrix A is strictly diagonally dominant and a linear system with a matrix of this form can be shown [▶ Theorem](#) to have a unique solution for $c_0, c_1, \dots, c_n$.

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Clamped Cubic Spline Algorithm

Context

To construct the cubic spline interpolant S for the function f defined at the numbers $x_0 < x_1 < \cdots < x_n$, satisfying

$$S'(x_0) = f'(x_0) \quad \text{and} \quad S'(x_n) = f'(x_n)$$

where

$$S(x) = S_j(x) = a_j + b_j(x - x_j) + c_j(x - x_j)^2 + d_j(x - x_j)^3$$

for $x_j \leq x \leq x_{j+1}$.

Clamped Cubic Spline Algorithm

INPUT $n; x_0, x_1, \dots, x_n; a_0 = f(x_0), a_1 = f(x_1), \dots, a_n = f(x_n);$
 $FPO = f'(x_0); FPN = f'(x_n).$

Clamped Cubic Spline Algorithm

INPUT $n; x_0, x_1, \dots, x_n; a_0 = f(x_0), a_1 = f(x_1), \dots, a_n = f(x_n);$
 $FPO = f'(x_0); FPN = f'(x_n).$

OUTPUT a_j, b_j, c_j, d_j for $j = 0, 1, \dots, n - 1$

Clamped Cubic Spline Algorithm

INPUT $n; x_0, x_1, \dots, x_n; a_0 = f(x_0), a_1 = f(x_1), \dots, a_n = f(x_n);$
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OUTPUT a_j, b_j, c_j, d_j for $j = 0, 1, \dots, n - 1$

Step 1 For $i = 0, 1, \dots, n - 1$ set $h_i = x_{i+1} - x_i$

Clamped Cubic Spline Algorithm

INPUT $n; x_0, x_1, \dots, x_n; a_0 = f(x_0), a_1 = f(x_1), \dots, a_n = f(x_n);$
 $FPO = f'(x_0); FPN = f'(x_n).$

OUTPUT a_j, b_j, c_j, d_j for $j = 0, 1, \dots, n-1$

Step 1 For $i = 0, 1, \dots, n-1$ set $h_i = x_{i+1} - x_i$

Step 2 Set $\alpha_0 = 3(a_1 - a_0)/h_0 - 3FPO$
 $\alpha_n = 3FPN - 3(a_n - a_{n-1})/h_{n-1}$

Clamped Cubic Spline Algorithm

INPUT $n; x_0, x_1, \dots, x_n; a_0 = f(x_0), a_1 = f(x_1), \dots, a_n = f(x_n);$
 $FPO = f'(x_0); FPN = f'(x_n).$

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Step 1 For $i = 0, 1, \dots, n-1$ set $h_i = x_{i+1} - x_i$

Step 2 Set $\alpha_0 = 3(a_1 - a_0)/h_0 - 3FPO$
 $\alpha_n = 3FPN - 3(a_n - a_{n-1})/h_{n-1}$

Step 3 For $i = 1, 2, \dots, n-1$
 set $\alpha_i = \frac{3}{h_i}(a_{i+1} - a_i) - \frac{3}{h_{i-1}}(a_i - a_{i-1})$

(Note: In what follows, Steps 4, 5, 6 and part of Step 7 solve a tridiagonal linear system using a Crout Factorization algorithm.)

Natural Cubic Spline Algorithm (Cont'd)

Step 4 Set $l_0 = 2h_0$
 $\mu_0 = 0.5$
 $z_0 = \alpha_0/l_0$

Natural Cubic Spline Algorithm (Cont'd)

Step 4 Set $l_0 = 2h_0$

$$\mu_0 = 0.5$$

$$z_0 = \alpha_0/l_0$$

Step 5 For $i = 1, 2, \dots, n-1$

$$\text{set } l_i = 2(x_{i+1} - x_{i-1}) - h_{i-1}\mu_{i-1}$$

$$\mu_i = h_i/l_i$$

$$z_i = (\alpha_i - h_{i-1}z_{i-1})/l_i$$

Natural Cubic Spline Algorithm (Cont'd)

Step 4 Set $l_0 = 2h_0$

$$\mu_0 = 0.5$$

$$z_0 = \alpha_0/l_0$$

Step 5 For $i = 1, 2, \dots, n-1$

$$\text{set } l_i = 2(x_{i+1} - x_{i-1}) - h_{i-1}\mu_{i-1}$$

$$\mu_i = h_i/l_i$$

$$z_i = (\alpha_i - h_{i-1}z_{i-1})/l_i$$

Step 6 Set $l_n = h_{n-1}(2 - \mu_{n-1})$

$$z_n = (\alpha_n - h_{n-1}z_{n-1})/l_n$$

$$c_n = z_n$$

Natural Cubic Spline Algorithm (Cont'd)

Step 4 Set $l_0 = 2h_0$

$$\mu_0 = 0.5$$

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Step 5 For $i = 1, 2, \dots, n-1$

$$\text{set } l_i = 2(x_{i+1} - x_{i-1}) - h_{i-1}\mu_{i-1}$$

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$$z_n = (\alpha_n - h_{n-1}z_{n-1})/l_n$$

$$c_n = z_n$$

Step 7 For $j = n-1, n-2, \dots, 0$

$$\text{set } c_j = z_j - \mu_j c_{j+1}$$

$$b_j = (a_{j+1} - a_j)/h_j - h_j(c_{j+1} + 2c_j)/3$$

$$d_j = (c_{j+1} - c_j)/(3h_j)$$

Natural Cubic Spline Algorithm (Cont'd)

Step 4 Set $l_0 = 2h_0$

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Step 5 For $i = 1, 2, \dots, n-1$

$$\text{set } l_i = 2(x_{i+1} - x_{i-1}) - h_{i-1}\mu_{i-1}$$

$$\mu_i = h_i/l_i$$

$$z_i = (\alpha_i - h_{i-1}z_{i-1})/l_i$$

Step 6 Set $l_n = h_{n-1}(2 - \mu_{n-1})$

$$z_n = (\alpha_n - h_{n-1}z_{n-1})/l_n$$

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Step 7 For $j = n-1, n-2, \dots, 0$

$$\text{set } c_j = z_j - \mu_j c_{j+1}$$

$$b_j = (a_{j+1} - a_j)/h_j - h_j(c_{j+1} + 2c_j)/3$$

$$d_j = (c_{j+1} - c_j)/(3h_j)$$

Step 8 OUTPUT $(a_j, b_j, c_j, d_j \text{ for } j = 0, 1, \dots, n-1)$ & STOP

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Clamped Cubic Spline for $f(x) = e^x$

Example: 3 Data Points

A previous [Example](#) used a natural spline and the data points

$$(0, 1), \quad (1, e), \quad (2, e^2) \quad \text{and} \quad (3, e^3)$$

to form a new approximating function $S(x)$. Determine the clamped spline $s(x)$ that uses this data and the additional information that, since $f'(x) = e^x$, so $f'(0) = 1$ and $f'(3) = e^3$.

Clamped Cubic Spline for $f(x) = e^x$

Solution (1/5)

As before, we have $n = 3$, $h_0 = h_1 = h_2 = 1$, $a_0 = 0$, $a_1 = e$, $a_2 = e^2$, and $a_3 = e^3$. This together with the information that $f'(0) = 1$ and $f'(3) = e^3$ gives the the matrix A and the vectors $\mathbf{b}$ and $\mathbf{x}$ with the forms [► Original Form](#) :

$$A = \begin{bmatrix} 2 & 1 & 0 & 0 \\ 1 & 4 & 1 & 0 \\ 0 & 1 & 4 & 1 \\ 0 & 0 & 1 & 2 \end{bmatrix} \quad \mathbf{b} = \begin{bmatrix} 3(e - 2) \\ 3(e^2 - 2e + 1) \\ 3(e^3 - 2e^2 + e) \\ 3e^2 \end{bmatrix} \quad \text{and} \quad \mathbf{x} = \begin{bmatrix} c_0 \\ c_1 \\ c_2 \\ c_3 \end{bmatrix}$$

Clamped Cubic Spline for $f(x) = e^x$

Solution (2/5)

The vector-matrix equation $A\mathbf{x} = \mathbf{b}$ is equivalent to the system of equations:

$$\begin{aligned}2c_0 + c_1 &= 3(e - 2), \\c_0 + 4c_1 + c_2 &= 3(e^2 - 2e + 1), \\c_1 + 4c_2 + c_3 &= 3(e^3 - 2e^2 + e), \\c_2 + 2c_3 &= 3e^2.\end{aligned}$$

Clamped Cubic Spline for $f(x) = e^x$

Solution (3/5)

Solving this system simultaneously for c_0 , c_1 , c_2 and c_3 gives, to 5 decimal places,

$$c_0 = \frac{1}{15}(2e^3 - 12e^2 + 42e - 59) = 0.44468,$$

$$c_1 = \frac{1}{15}(-4e^3 + 24e^2 - 39e + 28) = 1.26548,$$

$$c_2 = \frac{1}{15}(14e^3 - 39e^2 + 24e - 8) = 3.35087,$$

$$c_3 = \frac{1}{15}(-7e^3 + 42e^2 - 12e + 4) = 9.40815.$$

Clamped Cubic Spline for $f(x) = e^x$

Step 7 For $j = n - 1, n - 2, \dots, 0$

set $c_j = z_j - \mu_j c_{j+1}$

$$b_j = (a_{j+1} - a_j)/h_j - h_j(c_{j+1} + 2c_j)/3$$

$$d_j = (c_{j+1} - c_j)/(3h_j)$$

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Clamped Cubic Spline for $f(x) = e^x$

Solution (5/5)

This gives the clamped cubic spine

$$s(x) = \begin{cases} 1 + x + 0.44468x^2 + 0.27360x^3 & \text{if } 0 \leq x < 1 \\ 2.71828 + 2.71016(x-1) + 1.26548(x-1)^2 + 0.69513(x-1)^3 & \text{if } 1 \leq x < 2 \\ 7.38906 + 7.32652(x-2) + 3.35087(x-2)^2 + 2.01909(x-2)^3 & \text{if } 2 \leq x \leq 3 \end{cases}$$

The graph of the clamped spline and $f(x) = e^x$ are so similar that no difference can be seen.

Outline

- 1 Introduction to Clamped Splines
- 2 Existence of a Unique Clamped Spline Interpolant
- 3 Clamped Cubic Spline Algorithm
- 4 Clamped Cubic Spline approximating $f(x) = e^x$
- 5 Clamped Cubic Spline approximating $\int_0^3 e^x dx$

Clamped Cubic Spline for $\int_0^3 e^x dx$

Example: The Integral of a Spline

Approximate the integral of $f(x) = e^x$ on $[0, 3]$, which has the value

$$\int_0^3 e^x dx = e^3 - 1 \approx 20.08553692 - 1 = 19.08553692,$$

by piecewise integrating the clamped cubic spline that approximates f on this interval.

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Note: From the previous example, the clamped cubic spine $s(x)$ that approximates $f(x) = e^x$ on $[0, 3]$ is described piecewise by

$$s(x) = \begin{cases} 1 + x + 0.44468x^2 + 0.27360x^3 & \text{if } 0 \leq x < 1 \\ 2.71828 + 2.71016(x-1) + 1.26548(x-1)^2 + 0.69513(x-1)^3 & \text{if } 1 \leq x < 2 \\ 7.38906 + 7.32652(x-2) + 3.35087(x-2)^2 + 2.01909(x-2)^3 & \text{if } 2 \leq x \leq 3 \end{cases}$$

Clamped Cubic Spline for $\int_0^3 e^x dx$

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Clamped Cubic Spline for $\int_0^3 e^x dx$

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Because the data is equally spaced, piecewise integrating the clamped spline results in the same formula as that for the natural cubic spline, that is:

$$\begin{aligned}\int_0^3 s(x) dx &= (a_0 + a_1 + a_2) + \frac{1}{2}(b_0 + b_1 + b_2) \\ &\quad + \frac{1}{3}(c_0 + c_1 + c_2) + \frac{1}{4}(d_0 + d_1 + d_2)\end{aligned}$$

Clamped Cubic Spline for $\int_0^3 e^x dx$

Solution (2/3)

Hence the integral approximation is

$$\begin{aligned}\int_0^3 s(x) dx &= (1 + 2.71828 + 7.38906) + \frac{1}{2}(1 + 2.71016 + 7.32652) \\ &\quad + \frac{1}{3}(0.44468 + 1.26548 + 3.35087) \\ &\quad + \frac{1}{4}(0.27360 + 0.69513 + 2.01909) \\ &= 19.05965.\end{aligned}$$

Clamped Cubic Spline for $\int_0^3 e^x dx$

Solution (3/3)

The absolute error in the integral approximation using the clamped and natural splines are

$$\text{Natural:} \quad |19.08554 - 19.55229| = 0.46675$$

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For integration purposes, the clamped spline is vastly superior. This should be no surprise since the boundary conditions for the clamped spline are exact, whereas for the natural spline we are essentially assuming that, since $f''(x) = e^x$,

$$0 = S''(x) \approx f''(0) = e^1 = 1 \quad \text{and} \quad 0 = S''(3) \approx f''(3) = e^3 \approx 20$$

Clamped Cubic Spline: Accuracy Statements

To conclude this section, we list an error-bound formula for the cubic spline with clamped boundary conditions. The proof of this result can be found in [Schul], pp. 57–58.

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Theorem

Let $f \in C^4[a, b]$ with $\max_{a \leq x \leq b} |f^{(4)}(x)| = M$. If S is the unique clamped cubic spline interpolant to f with respect to the nodes $a = x_0 < x_1 < \cdots < x_n = b$, then for all x in $[a, b]$,

$$|f(x) - S(x)| \leq \frac{5M}{384} \max_{0 \leq j \leq n-1} (x_{j+1} - x_j)^4$$

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A fourth-order error-bound result also holds in the case of natural boundary conditions, but it is more difficult to express.

Clamped Cubic Spline: Accuracy Statements

Natural Boundary Conditions: Final Remark

The natural boundary conditions will generally give less accurate results than the clamped conditions near the ends of the interval $[x_0, x_n]$ unless the function f happens to nearly satisfy

$$f''(x_0) = f''(x_n) = 0$$

Questions?

Reference Material

Natural Cubic Spline

Example: 3 Data Values

Construct a natural cubic spline that passes through the points (1, 2), (2, 3), and (3, 5).

The Resulting Spline

$$S(x) = \begin{cases} 2 + \frac{3}{4}(x - 1) + \frac{1}{4}(x - 1)^3, & \text{for } x \in [1, 2] \\ 3 + \frac{3}{2}(x - 2) + \frac{3}{4}(x - 2)^2 - \frac{1}{4}(x - 2)^3, & \text{for } x \in [2, 3] \end{cases}$$

[◀ Return to Clamped Spline Example](#)

Strictly Diagonally Dominant Matrices

Theorem

- A strictly diagonally dominant matrix A is nonsingular.
- Moreover, in this case, Gaussian elimination can be performed on any linear system of the form $A\mathbf{x} = \mathbf{b}$ to obtain its unique solution without row or column interchanges, and the computations will be stable with respect to the growth of round-off errors.

[◀ Return to Clamped Spline Uniqueness Proof](#)

Clamped Spline Interpolant: Linear System $A\mathbf{x} = \mathbf{b}$

$$A = \begin{bmatrix} 2h_0 & h_0 & 0 & \cdots & \cdots & 0 \\ h_0 & 2(h_0 + h_1) & h_1 & \ddots & & \vdots \\ 0 & h_1 & 2(h_1 + h_2) & h_2 & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \ddots & 0 \\ \vdots & & \ddots & h_{n-2} & 2(h_{n-2} + h_{n-1}) & h_{n-1} \\ 0 & \cdots & \cdots & 0 & h_{n-1} & 2h_{n-1} \end{bmatrix}$$
$$\mathbf{b} = \begin{bmatrix} \frac{3}{h_0}(a_1 - a_0) - 3f'(a) \\ \frac{3}{h_1}(a_2 - a_1) - \frac{3}{h_0}(a_1 - a_0) \\ \vdots \\ \frac{3}{h_{n-1}}(a_n - a_{n-1}) - \frac{3}{h_{n-2}}(a_{n-1} - a_{n-2}) \\ 3f'(b) - \frac{3}{h_{n-1}}(a_n - a_{n-1}) \end{bmatrix} \quad \text{with } \mathbf{x} = \begin{bmatrix} c_0 \\ c_1 \\ \vdots \\ c_n \end{bmatrix}$$

Natural Spline Interpolant

Example: $f(x) = e^x$

Use the data points $(0, 1)$, $(1, e)$, $(2, e^2)$, and $(3, e^3)$ to form a natural spline $S(x)$ that approximates $f(x) = e^x$.

Answer

The natural cubic spine is described piecewise by

$$S(x) = \begin{cases} 1 + 1.46600x + 0.25228x^3 & \text{for } x \in [0, 1] \\ 2.71828 + 2.22285(x - 1) + 0.75685(x - 1)^2 + 1.69107(x - 1)^3 & \text{for } x \in [1, 2] \\ 7.38906 + 8.80977(x - 2) + 5.83007(x - 2)^2 - 1.94336(x - 2)^3 & \text{for } x \in [2, 3] \end{cases}$$

[Return to Clamped Spline Example \(\$f\(x\) = e^x\$ \)](#)